Analyzing Ion Dynamics in Muscle Contraction: Expanding on Electrophysiology in the 1981 Morris-Lecar Model

Background

- muscle contraction.

- contraction.





$\overline{\mathrm{d}t} = C^{-1} [I - g_L V_L + g_{Ca} M V (V - V_{Ca}) + g_K N V (V - V_K)]$	(1)
$\frac{dM}{dt} = \lambda_M (V) [M_\infty(V) - M]$	(2)
$\frac{dN}{dt} = \lambda_N (V) [N_\infty(V) - N]$	(3)

$\frac{dV}{dt} = C^{-1}[I - g_L V_L + g_K \mu V (V - V_K)]$	(4)
$\frac{d\mu}{dt} = \lambda_{\mu} \left(V \right) \left[\mu_{\infty}(V) - \mu \right]$	(5)



Thank you Dr. Leiderman for all your support and advice!



Results



Figure 4: Original experimental Morris-Lecar data for Ca++. only voltage dynamics. Description from Morris-Lecar: Responses of a fiber to two subsequent current stimuli (360 μ A) 1 min apart (upper trace first). Duration of the stimulus is 100ms.



Figure 5. Example Trajectories Computed for the Joint K+ and Ca++ System. MATLAB computed model for voltage response to various applied currents with nullclines for the ODE system also plotted. The plots represent numerical solutions to the full V, M, N ODE system (Eqns. 1-3) with values for the parameters as follows: gK = 12, gCa = 6, gL = 2, V1 = 0, V2 = 15, V3 = 10, V4 = 10, $\lambda N = 0.1$, $\lambda M = 1$, C = 20, VL = -50, VK = -70, VCa = 100. And the initial conditions used for the system were V(0) = -50, N(0) = Ninf(-50), and M(0) = Minf(-50). A) Limit Cycle Oscillation. ODE system with parameters listed above and applied current of 30 µA. B) Damped **Oscillation.** ODE system with parameters listed above and applied current of 55 μ A.



- current model, such as: oscillations that grow over time, bistable oscillation patterns, and amplitude modulated oscillations • The perfect space clamp approach of the Morris-Lecar model might oversimplify the intricate dynamics
- for in the current model

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- Capturing more complex oscillatory behaviors not observed with the
- Investigating ion accumulation and additional conductances not accounted